Galaxies Part II

Before we start modelling

Basics

Binary star orbits

General orbit under radial force law

Stellar Dynamics and Structure of Galaxies Orbits in a given potential

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Outline I

Before we start modelling stellar systems

Basics

Binary star orbit

General orbit under radi force law 1 Before we start modelling stellar systems

Collisions

Model requirements

2 Basics

Newton's law

Orbits

Orbits in spherical potentials

Equation of motion in two dimensions

Path of the orbit

Energy per unit mass

Kepler's Laws

Unbound orbits

Escape velocity

- 3 Binary star orbits
- 4 General orbit under radial force law

Orbital periods

Example

Before we start modelling

Collisions

Model requirements

Basics

Binary star orbit

General orbit under radi

Collisions Do we have to worry about collisions?



Globular clusters look densest, so obtain a rough estimate of collision timescale for them

Collisions

Model requiremen

Basics

Binary star orbit

General orbit under radi force law

Collisions in globular clusters

The case of NGC 2808

$$ho_0 \sim 8 \times 10^4 \ {\rm M_{\odot} \ pc^{-3}}$$
 $M_* \sim 0.8 \ {\rm M_{\odot}}.$ $\Rightarrow n_0 \sim 10^5 \ {\rm pc^{-3}}$ is the star number density. We have $\sigma_r \sim 13 \ {\rm km \ s^{-1}}$ as the typical 1D speed of a star, so the 3D speed is $\sim \sqrt{3} \times \sigma_r \ (= \sqrt{\sigma_x^2 + \sigma_y^2 + \sigma_z^2}) \sim 20 \ {\rm km \ s^{-1}}.$ Since $M_* \propto R_*$ (see Fluids, or Stars, course notes), have $R_* \sim 0.8 R_{\odot}.$

Before we start modelling

Collisions

Model requirement

Binary star orbits

General orbit under rad force law

Collisions in globular clusters

The case of NGC 2808

For a collision, need the volume $\pi(2R_*)^2\sigma t_{\rm coll}$ to contain one star, i.e.

$$n_0 = 1/\left(\pi (2R_*)^2 \sigma t_{\text{coll}}\right)$$
 (1.1)

or

$$t_{\rm coll} = 1/\left(4\pi R_*^2 \sigma n_0\right) \tag{1.2}$$

$$R_* = 0.8R_{\odot}$$
, $n_0 = 10^5 pc^{-3}$, $\sigma = 20 km/s$

Putting in the numbers gives $t_{\rm coll} \sim 10^{14}$ yr.

So direct collisions between stars are rare, but if you have $\sim 10^6$ stars then there is a collision every $\sim 10^8$ years, so they \underline{do} happen.

Note that NGC 2808 is 10 times denser than typical

So, for now, ignore collisions, and we are left with stars orbiting in the potential from all the other stars in the system.

Before we start modelling

Collisions Model requirements

Rasics

Binary star orbit

General orbit under rad

Model requirements

Model (e.g., a globular cluster) just as a self-gravitating collection of objects.

Have a gravitational potential well $\Phi(\mathbf{r})$, approximately smooth if the number of particles >> 1. Conventionally take $\Phi(\infty)=0$.

Stars orbit in the potential well, with time per orbit (for a globular cluster) $\sim 2R_b/\sigma \sim 10^6$ years << age.

Remember how to measure age for globular clusters?

Stars give rise to $\Phi(\mathbf{r})$ by their mass, so for this potential in a steady state could average each star over its orbit to get $\rho(\mathbf{r})$.

The key problem is therefore self-consistently building a model which fills in the terms:

$$\Phi(\mathbf{r}) \to \text{ stellar orbits} \to \rho(\mathbf{r}) \to \Phi(\mathbf{r})$$
 (1.3)

Note that in most observed cases we only have $v_{\text{line of sight}}(R)$, so it is even harder to model real systems.

Self-consistent = orbits & stellar mass give ρ , which leads to Φ , which supports the orbits used to construct ρ

Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in
two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws
Unbound orbits

Binary star orbit

General orbit under radia force law

The law of attraction

Newton's laws of motion and Newtonian gravity

GR not needed, since

- $10 < \overline{v} < 10^3 \ {
 m \frac{km}{s}}$ is $<< c = 3 imes 10^5 \ {
 m \frac{km}{s}}$
- $\frac{GM}{rc^2} \sim ???$

The gravitational force per unit mass acting on a body due to a mass M at the origin is

$$\mathbf{f} = -\frac{GM}{r^2}\hat{\mathbf{r}} = -\frac{GM}{r^3}\mathbf{r} \tag{1.4}$$

We can write this in terms of a potential Φ , using

$$\nabla\left(\frac{1}{r}\right) = -\frac{1}{r^2}\hat{\mathbf{r}}\tag{1.5}$$

Basics

Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit Energy per unit mass Kepler's Laws

Binary star orbit

General orbit under radia

The corresponding potential

So

$$\mathbf{f} = -\nabla \Phi \tag{1.6}$$

where Φ is a scalar.

$$\Phi = \Phi(r) = -\frac{GM}{r} \tag{1.7}$$

Hence the potential due to a point mass M at $\mathbf{r} = \mathbf{r}_1$ is

$$\Phi(\mathbf{r}) = -\frac{GM}{|\mathbf{r} - \mathbf{r}_1|} \tag{1.8}$$

Before we start modelling

Basics

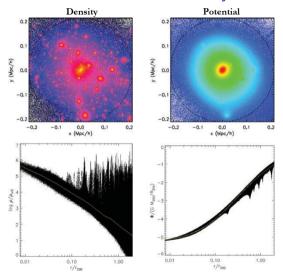
Newton's law

Orbits
Orbits in spherical potentials
Equation of motion is two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws
Unbound orbits
Energy per deposits

Binary star orbit

General orbit under radi

Density vs Potential



From Hayashi et al, "The shape of the gravitational potential in cold dark matter haloes"

Before we start modelling

Basics

Newton's law

Orbits
Orbits in spherical potentials
Equation of motion it two dimensions
Path of the orbit

Energy per unit ma Kepler's Laws Unbound orbits

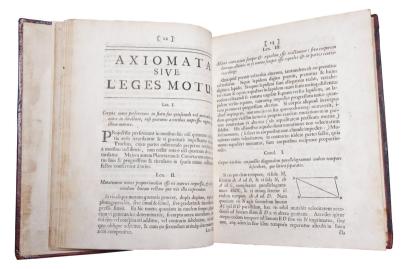
Unbound orbits

Binary star orbit

General orbit under rad force law

Orbits

The law of motion



Basics

Newton's la

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws

Binary star orbit

General orbit under radia

Particle of constant mass m at position \mathbf{r} subject to a force \mathbf{F} . Newton's law:

$$\frac{d}{dt}\left(m\dot{\mathbf{r}}\right) = \mathbf{F} \tag{1.9}$$

Orbits

i.e.

$$m\ddot{\mathbf{r}} = \mathbf{F}$$
 (1.10)

If **F** is due to a gravitational potential $\Phi(\mathbf{r})$, then

$$\mathbf{F} = m\mathbf{f} = -m\nabla\Phi \tag{1.11}$$

The angular momentum about the origin is $\mathbf{H} = \mathbf{r} \times (m\dot{\mathbf{r}})$. Then

$$\frac{d\mathbf{H}}{dt} = \mathbf{r} \times (m\ddot{\mathbf{r}}) + m\dot{\mathbf{r}} \times \dot{\mathbf{r}}$$
$$= \mathbf{r} \times \mathbf{F}$$
$$\equiv \mathbf{G}$$

(1.12)

where G is the torque about the origin.

Orbits

Before we start modelling stellar systems

Basics

Newton's la

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws

Binary star orbit

General orbit under radia force law

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Before we start modelling

Basics

Newton's law

Orbits Orbits in spherical

potentials
Equation of motion in two dimensions
Path of the orbit

Energy per unit ma

Escape velocit

Binary star orbit

General orbit under radia force law

Energy

The kinetic energy

$$T = \frac{1}{2}m\dot{\mathbf{r}} \cdot \dot{\mathbf{r}} \tag{1.13}$$

$$\frac{dT}{dt} = m\dot{\mathbf{r}} \cdot \ddot{\mathbf{r}} = \mathbf{F} \cdot \dot{\mathbf{r}} \tag{1.14}$$

If $\mathbf{F} = -m\nabla\Phi$, then

$$\frac{dT}{dt} = -m\dot{\mathbf{r}} \cdot \nabla \Phi(\mathbf{r}) \tag{1.15}$$

But if Φ is independent of t, the rate of change of Φ along an orbit is

$$\frac{d}{dt}\Phi(\mathbf{r}) = \nabla\Phi \cdot \dot{\mathbf{r}} \tag{1.16}$$

from the chain rule

Before we start modelling

Basics

Newton's lav

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws

Binary star orbit

General orbit under radia force law

Energy

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Basics

Newton's law

Orbits
Orbits in spherical

potentials

Equation of motion i

Path of the orbit

Kepler's Laws

Unbound orbits

Binary star orbits

General orbit under radia

Hence

$$\frac{dT}{dt} = -m\frac{d}{dt}\Phi(\mathbf{r}) \tag{1.17}$$

$$\Rightarrow m\frac{d}{dt}\left(\frac{1}{2}\dot{\mathbf{r}}\cdot\dot{\mathbf{r}} + \Phi(\mathbf{r})\right) = 0 \tag{1.18}$$

$$\Rightarrow E = \frac{1}{2}\dot{\mathbf{r}} \cdot \dot{\mathbf{r}} + \Phi(\mathbf{r}) \tag{1.19}$$

The total energy is constant for a given orbit

Basics

Newton's law Orbits

Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit

Energy per unit mass Kepler's Laws

Unbound orbits

Binary star orbits

General orbit under radia

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Basics

Orbits
Orbits in spherical potentials

potentials

Equation of motion in two dimensions

Path of the orbit

Energy per unit mass

Kepler's Laws

Unbound orbits

Escape velocity

Binary star orbi

General orbit under radia force law

Orbits in spherical potentials

$$\Phi(\mathbf{r}) = \Phi(|\mathbf{r}|) = \Phi(r)$$
, so $\mathbf{f} = -\nabla \Phi = -\hat{\mathbf{r}} \frac{d\Phi}{dr}$.
The orbital angular momentum $\mathbf{H} = m\mathbf{r} \times \dot{\mathbf{r}}$, and

$$\frac{d\mathbf{H}}{dt} = \mathbf{r} \times m\mathbf{f} = -m\frac{d\Phi}{dr}\mathbf{r} \times \hat{\mathbf{r}} = 0. \tag{1.20}$$

So the angular momentum per unit mass $\mathbf{h} = \mathbf{H}/m = \mathbf{r} \times \dot{\mathbf{r}}$ is a constant vector, and is perpendicular to \mathbf{r} and $\dot{\mathbf{r}}$

 \Rightarrow the particle stays in a plane through the origin which is perpendicular to **h**

Check: $\mathbf{r} \perp \mathbf{h}$, $\mathbf{r} + \delta \mathbf{r} = \mathbf{r} + \dot{\mathbf{r}} \delta t \perp \mathbf{h}$ since both \mathbf{r} and $\dot{\mathbf{r}} \perp \mathbf{h}$, so particle remains in the plane

Thus the problem becomes a two-dimensional one to calculate the orbit use 2-D cylindrical coordinates (R, ϕ, z) at z = 0, or spherical polars (r, θ, ϕ) with $\theta = \frac{\pi}{2}$. So, in 2D, use (R, ϕ) and (r, ϕ) interchangeably.

Basics

Newton's law Orbits Orbits in spherical

Equation of motion in two dimensions

Path of the orbit
Energy per unit mass
Kepler's Laws
Unbound orbits
Escape velocity

Binary star orbit

General orbit under radia

Equation of motion in two dimensions

The equation of motion in two dimensions can be written in radial angular terms, using $\mathbf{r} = r\hat{\mathbf{e}}_r + 0\hat{\mathbf{e}}_{\phi}$, so $\mathbf{r} = (r, 0)$.

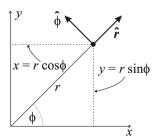
We know that

$$\frac{d}{dt}\hat{\mathbf{e}}_r = \dot{\phi}\hat{\mathbf{e}}_{\phi} \tag{1.21}$$

and

$$\frac{d}{dt}\hat{\mathbf{e}}_{\phi} = -\dot{\phi}\hat{\mathbf{e}}_{r} \tag{1.22}$$

$$\hat{\mathbf{e}}_{r} = \cos(\phi)\hat{\mathbf{e}}_{x} + \sin(\phi)\hat{\mathbf{e}}_{y}
\hat{\mathbf{e}}_{\phi} = -\sin(\phi)\hat{\mathbf{e}}_{x} + \cos(\phi)\hat{\mathbf{e}}_{y}
\frac{d}{dt}\hat{\mathbf{e}}_{r} = -\sin(\phi)\dot{\phi}\hat{\mathbf{e}}_{x} + \cos(\phi)\dot{\phi}\hat{\mathbf{e}}_{y}
\frac{d}{dt}\hat{\mathbf{e}}_{\phi} = -\cos(\phi)\dot{\phi}\hat{\mathbf{e}}_{x} - \sin(\phi)\dot{\phi}\hat{\mathbf{e}}_{y}$$



Basics

Newton's law Orbits Orbits in spherical

Equation of motion in two dimensions

Path of the orbit Energy per unit mas Kepler's Laws Unbound orbits Escape velocity

Binary star orbit

General orbit under radia force law

Equation of motion in two dimensions

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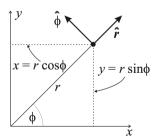
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and

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$$\begin{array}{lll} \hat{\mathbf{e}}_{r} & = & \cos(\phi)\hat{\mathbf{e}}_{x} + \sin(\phi)\hat{\mathbf{e}}_{y} \\ \hat{\mathbf{e}}_{\phi} & = & -\sin(\phi)\hat{\mathbf{e}}_{x} + \cos(\phi)\hat{\mathbf{e}}_{y} \\ \frac{d}{dt}\hat{\mathbf{e}}_{r} & = & -\sin(\phi)\dot{\phi}\hat{\mathbf{e}}_{x} + \cos(\phi)\dot{\phi}\hat{\mathbf{e}}_{y} \\ \frac{d}{dt}\hat{\mathbf{e}}_{\phi} & = & -\cos(\phi)\dot{\phi}\hat{\mathbf{e}}_{x} - \sin(\phi)\dot{\phi}\hat{\mathbf{e}}_{y} \end{array}$$



Basics

Newton's law
Orbits
Orbits in spherical
potentials

Equation of motion in two dimensions

Path of the orbit Energy per unit mass Kepler's Laws Unbound orbits Escape velocity

Binary star orbi

General orbit under radia force law

Equation of motion in two dimensions

Hence

$$\dot{\mathbf{r}} = \dot{r}\hat{\mathbf{e}}_r + r\dot{\phi}\hat{\mathbf{e}}_{\phi} \tag{1.23}$$

or
$$\dot{f r}={f v}=\!(\dot{r},r\dot{\phi})$$

and so

$$\ddot{\mathbf{r}} = \ddot{r}\hat{\mathbf{e}}_{r} + \dot{r}\dot{\phi}\hat{\mathbf{e}}_{\phi} + \dot{r}\dot{\phi}\hat{\mathbf{e}}_{\phi} + r\ddot{\phi}\hat{\mathbf{e}}_{\phi} - \dot{r}\dot{\phi}^{2}\hat{\mathbf{e}}_{r}$$

$$= (\ddot{r} - \dot{r}\dot{\phi}^{2})\hat{\mathbf{e}}_{r} + \frac{1}{r}\frac{d}{dt}\left(r^{2}\dot{\phi}\right)\hat{\mathbf{e}}_{\phi}$$

$$= \mathbf{a} = [\ddot{r} - \dot{r}\dot{\phi}^{2}, \frac{1}{r}\frac{d}{dt}\left(r^{2}\dot{\phi}\right)]$$

(1.24)

In general $\mathbf{f}=(f_r,f_\phi)$, and then $f_r=\ddot{r}-r\dot{\phi}^2$, where the second term is the centrifugal force, since we are in a rotating frame, and the torque $rf_\phi=\frac{d}{dt}\left(r^2\dot{\phi}\right) \ (=\mathbf{r}\times\mathbf{f})$. In a spherical potential $f_\phi=0$, so $r^2\dot{\phi}$ is constant.

Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in
two dimensions

Path of the orbit Energy per unit mass

Kepler's Laws Unbound orbits Escape velocity

Binary star orbit

General orbit under radia force law

Path of the orbit

To determine the shape of the orbit we need to remove t from the equations and find $r(\phi)$. It is simplest to set u=1/r, and then from $r^2\dot{\phi}=h$ obtain

$$\dot{\phi} = hu^2 \tag{1.25}$$

Then

$$\dot{r} = -\frac{1}{u^2}\dot{u} = -\frac{1}{u^2}\frac{du}{d\phi}\dot{\phi} = -h\frac{du}{d\phi}$$
 (1.26)

and

$$\ddot{r} = -h \frac{d^2 u}{d\phi^2} \dot{\phi} = -h^2 u^2 \frac{d^2 u}{d\phi^2}.$$
 (1.27)

Path of the orbit Energy per unit mass Kepler's Laws

Kepler's Laws
Unbound orbits
Escape velocity

Binary star orbit

General orbit under radia force law

Path of the orbit

So the radial equation of motion

$$\ddot{r} - r\dot{\phi}^2 = f_r$$

becomes

$$-h^2 u^2 \frac{d^2 u}{d\phi^2} - \frac{1}{u} h^2 u^4 = f_r \tag{1.28}$$

$$\Rightarrow \frac{d^2u}{d\phi^2} + u = -\frac{f_r}{h^2u^2} \tag{1.29}$$

The orbit equation in spherical potential

Basics

Orbits
Orbits in spherical potentials
Equation of motion in

Path of the orbit Energy per unit ma

Unbound orbits Escape velocity

Binary star orbit

Dillary Star Orbit

General orbit under radia force law

Path of the orbit

Since f_r is just a function of r (or u) this is an equation for $u(\phi)$, i.e. $r(\phi)$ - the <u>path</u> of the orbit. Note that it does not give r(t), or $\phi(t)$ - you need one of the other equations for those.

If we take $f_r = -\frac{GM}{r^2} = -GMu^2$, then

$$\frac{d^2u}{d\phi^2} + u = GM/h^2 \tag{1.30}$$

(which is something you will have seen in the Relativity course).

Basics

Orbits
Orbits in spherical potentials
Equation of motion in

Path of the orbit Energy per unit mas

Kepler's Laws Unbound orbits Escape velocity

Dillary Star Orb

General orbit under radia force law

Kepler orbits

Solution to the equation of motion

The solution to this equation is

$$\frac{\ell}{r} = \ell u = 1 + e \cos(\phi - \phi_0)$$
 (1.31)

which you can verify simply by putting it in the differential equation. Then

$$-\frac{e\cos(\phi-\phi_0)}{\ell}+\frac{1+e\cos(\phi-\phi_0)}{\ell}=\frac{GM}{h^2}$$

so $\ell=h^2/GM$ and e and ϕ_0 are constants of integration.

Galaxies Part II

Before we start modelling stellar systems

Basics

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions

Path of the orbit Energy per unit ma

Kepler's Laws
Unbound orbits
Escape velocity

Binary star orb

General orbit under radia force law

Kepler orbits

$$\frac{1}{r} = \frac{1 + e\cos(\phi - \phi_0)}{\ell}$$

Note that if e < 1 then 1/r is never zero, so r is bounded in the range $\frac{\ell}{1+e} < r < \frac{\ell}{1-e}$. Also, in all cases the orbit is symmetric about $\phi = \phi_0$, so we take $\phi_0 = 0$ as defining the reference line for the angle ϕ . ℓ is the distance from the origin for $\phi = \pm \frac{\pi}{2}$ (with ϕ measured relative to ϕ_0).

Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in

Path of the orbit Energy per unit mas Kepler's Laws

Kepler's Laws Unbound orbits Escape velocity

Binary star orbit

General orbit under radia force law

Kepler orbits

Bound orbits

We can use different parameters. Knowing that the point of closest approach (perihelion for a planet in orbit around the Sun, periastron for something about a star) is at $\ell/(1+e)$ when $\phi=0$ and the aphelion (or whatever) is at $\ell/(1-e)$ when $\phi=\pi$, we can set the distance between these two points (= major axis of the orbit)=2a. Then

$$\frac{\ell}{1+e} + \frac{\ell}{1-e} = 2a \Rightarrow \ell(1-e) + \ell(1+e) = 2a(1-e^2)$$
 (1.32)

$$\Rightarrow \ell = a(1 - e^2) \tag{1.33}$$

 \Rightarrow $r_P = a(1-e)$ is the perihelion distance from the gravitating mass at the origin, and $r_a = a(1+e)$ is the aphelion distance. The distance of the Sun from the midpoint is ae, and the angular momentum $h^2 = GM\ell = GMa(1-e^2)$.

Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in
two dimensions
Path of the orbit

Path of the orbit Energy per unit mass Kepler's Laws Unbound orbits

Binary star orbits

General orbit under radia force law

Energy per unit mass

The energy per unit mass

$$E = \frac{1}{2}\dot{\mathbf{r}} \cdot \dot{\mathbf{r}} + \Phi(\mathbf{r}) = \frac{1}{2}\dot{r}^2 + \frac{1}{2}r^2\dot{\phi}^2 - \frac{GM}{r}$$
 (1.34)

$$r_p = a(1-e)$$

This is constant along the orbit, so we can evaluate it anywhere convenient - e.g. at perihelion where $\dot{r}=0$. Then $\dot{\phi}=\frac{h}{r_0^2}$ and so

$$E = \frac{1}{2} \frac{GMa(1-e^2)}{a^2(1-e)^2} - \frac{GM}{a(1-e)}$$
$$= \frac{GM}{a} \left[\frac{1}{2} \left(\frac{1+e}{1-e} \right) - \frac{1}{1-e} \right]$$
$$= -\frac{GM}{2a}$$

(1.35)

This is < 0 for a bound orbit, and depends only on the semi-major axis a (and not e).

Galaxies Part II

Before we start modelling stellar systems

Basics

Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit

Energy per unit m

Kepler's Laws

Escape velocity

Binary star orbits

General orbit under radia force law

Kepler's Laws

... deduced from observations, and explained by Newtonian theory of gravity.

Basics

Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit

Kepler's Laws

Unbound or

Dinary Star Gron

General orbit under radia force law

Kepler's Laws

1 Orbits are ellipses with the Sun at a focus.

2 Planets sweep out equal areas in equal time

$$\delta A = \frac{1}{2}r^2\delta\phi \ [=\frac{1}{2}r(r\delta\phi)] \tag{1.36}$$

$$\frac{dA}{dt} = \frac{1}{2}r^2\dot{\phi} = \frac{h}{2} = \text{constant}$$
 (1.37)

 \Rightarrow Kepler's second law is a consequence of a central force, since this is why h is a constant

Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in
two dimensions
Path of the orbit

Kepler's Laws

Unbound or

Dinanc star orbi

General orbit under radia force law

Kepler's Laws

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Basics

Newton's law
Orbits
Orbits in spherical
potentials
Equation of motion in
two dimensions
Path of the orbit

Kepler's Laws

Unbound orbits Escape velocity

Binary star or

General orbit under radia force law

Kepler's Laws

3rd Law

3 (Period)² \propto (size of orbit)³

In one period T, the area swept out is $A = \frac{1}{2}hT = \left(\int_0^T \frac{dA}{dt}dt\right)$

But A= area of ellipse $=\pi ab=\pi a^2\sqrt{1-e^2}$

$$A = \int_0^{2\pi} d\phi \int_0^r r dr$$
$$= \int_0^{2\pi} \frac{1}{2} r^2 d\phi$$

$$\boxed{\frac{\ell}{r} = \ell u = 1 + e\cos(\phi - \phi_0)}$$

$$=\frac{\ell^2}{2}\int_0^{2\pi}\frac{d\phi}{(1+e\cos\phi)^2}$$

Have

$$\int_0^{\pi} \frac{dx}{(a+b\cos x)^2} = \frac{\pi}{a^2 - b^2} \frac{a}{\sqrt{a^2 - b^2}}$$

Galaxies Part II

Before we start modelling

Basics Newton's law

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit

Kepler's Laws

Unbound orbit Escape velocity

Binary star orl

General orbit under radia force law

Kepler's Laws 3rd Law

SO

$$A = 2\frac{\ell^2}{2} \frac{\pi}{1 - e^2} \frac{1}{\sqrt{1 - e^2}}$$

Since $\ell = a(1 - e^2)$ this implies

$$A = \pi a^2 \sqrt{1 - e^2}$$

 $def: e = \sqrt{1 - \frac{b^2}{a^2}}$

and since
$$b = a\sqrt{1 - e^2}$$
,

$$A = \pi ab$$

]

3rd Law

Basics

Orbits
Orbits in spherical potentials
Equation of motion

Energy per unit mass

Kepler's Laws

Escape velocity

Binary star orl

General orbit under radial force law

Therefore

$$T = \frac{2A}{h}$$

$$= \frac{2\pi a^2 \sqrt{1 - e^2}}{h}$$

$$= \frac{2\pi a^2 \sqrt{1 - e^2}}{\sqrt{GMa(1 - e^2)}}$$
since $h^2 = GMa(1 - e^2)$

$$T = 2\pi \sqrt{\frac{a^3}{GM}}$$

$$\Rightarrow T^2 \propto a^3$$
 (1.38)

where in this case M is the mass of the Sun.

Note: Since $E = -\frac{GM}{2a}$, the period $T = \frac{2\pi GM}{(-2E)^{\frac{3}{2}}}$.

Orbits in spherical

Unbound orbits

Unbound orbits

What happens to $\frac{\ell}{\epsilon} = 1 + e \cos \phi$ when $e \ge 1$?

- If e > 1 then $1 + e \cos \phi = 0$ has solutions ϕ_{∞} where $r = \infty \to \cos \phi_{\infty} = -1/e$
- If e=1 then the particle just gets to infinity at $\phi=\pm\pi$ it is a parabola.

Basics

Orbits
Orbits in spherical
potentials
Equation of motion i
two dimensions
Path of the orbit
Energy per unit mass

Unbound orbits Escape velocity

Dinary Star Gran

General orbit under radia force law

Unbound orbits

What happens to $rac{\ell}{r}=1+e\cos\phi$ when $e\geq 1$?

- If e>1 then $1+e\cos\phi=0$ has solutions ϕ_∞ where $r=\infty\to\cos\phi_\infty=-1/e$ Then $-\phi_\infty\le\phi\le\phi_\infty$, and, since $\cos\phi_\infty$ is negative, $\frac{\pi}{2}<\phi_\infty<\pi$. The orbit is a hyperbola.
- If e=1 then the particle just gets to infinity at $\phi=\pm\pi$ it is a parabola.

Orbits in spherical

Unbound orbits

Unbound orbits

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- If e=1 then the particle just gets to infinity at $\phi=\pm\pi$ it is a parabola.

Galaxies Part II

Before we start modelling

Basics

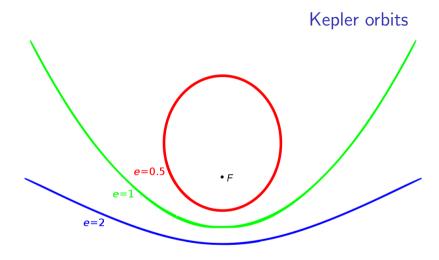
Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit Energy per unit mass Kepler's Laws

Unbound orbits

Escape velocity

Binary star ort

General orbit under radia force law



 $e=\infty$

Before we start modelling stellar systems

Basics Newton's law

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit

Kepler's Laws

Unbound orbits

Escape velocity

Binary star orb

General orbit under radi

Energies for these unbound orbits:

$$E = \frac{1}{2}\dot{r}^2 + \frac{1}{2}\frac{h^2}{r^2} - \frac{GM}{r}$$

So, as
$$r o \infty$$
 $E o rac{1}{2}\dot{r}^2$

$$r^2\dot{\phi}=h$$

Before we start modelling stellar systems

Basics

Orbits
Orbits in spherical potentials
Equation of motion in two dimensions
Path of the orbit

Unbound orbits

Escape velocity

Binary star orb

General orbit under radia force law

Recall

$$\frac{\ell}{r} = 1 + e\cos\phi$$

$$\frac{d}{dt}$$
 of this \Rightarrow

$$-\frac{\ell}{r^2}\dot{r} = -e\sin\phi\ \dot{\phi}$$

and since
$$h=r^2\dot{\phi}$$

$$\dot{r} = \frac{eh}{\ell} \sin \phi$$

As $r \to \infty \cos \phi \to -1/e$

$$E o rac{1}{2}\dot{r}^2 = rac{1}{2}rac{e^2h^2}{\ell^2}\left(1 - rac{1}{e^2}
ight) = rac{GM}{2\ell}(e^2 - 1)$$

(recalling that $h^2=GM\ell$) Thus E>0 if e>1 and for parabolic orbits (e=1) E=0.

Before we start modelling

Basics

Newton's law
Orbits in spherical
potentials
Equation of motion in
two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws
Unbound orbits
Escape velocity

Binary star orbit

General orbit under rac

Escape velocity

We have seen that in a fixed potential $\Phi(\mathbf{r})$ a particle has constant energy $E=\frac{1}{2}\dot{\mathbf{r}}^2+\Phi(\mathbf{r})$ along an orbit. If we adopt the usual convention and take $\Phi(\mathbf{r})\to 0$ as $|\mathbf{r}|\to \infty$, then if at some point \mathbf{r}_0 the particle has velocity \mathbf{v}_0 such that

$$\frac{1}{2}\mathbf{v}_0^2 + \Phi(\mathbf{r}_0) > 0$$

then it is <u>able</u> to reach infinity. So at each point \mathbf{r}_0 we can define an escape velocity $\mathbf{v}_{\rm esc}$ such that

$$v_{\rm esc} = \sqrt{-2\Phi(\mathbf{r}_0)}$$

Before we start modelling stellar systems

Basics

Newton's law
Orbits or spherical
potentials
Equation of motion in
two dimensions
Path of the orbit
Energy per unit mass
Kepler's Laws
Unbound orbits

Escape velocity
Binary star orbit

General orbit under radia force law

Escape velocity

From the Solar neighborhood

The escape velocity from the Sun

$$v_{\rm esc} = \left(\frac{2GM_{\odot}}{r_0}\right)^{\frac{1}{2}} = 42.2 \left(\frac{r_0}{\rm a.u.}\right)^{-\frac{1}{2}} {\rm ~km~s^{-1}}$$

Note: The circular velocity $v_{\rm circ}$ is such that $-r\dot{\phi}^2=-rac{GM}{r^2}$

$$r\dot{\phi} = v_{\rm circ} = \sqrt{\frac{GM_{\odot}}{r_0}} = 29.8 \left(\frac{r_0}{\rm a.u.}\right)^{-\frac{1}{2}} {\rm km \ s^{-1}}$$

 $(= 2\pi \text{ a.u./yr}).$

 $v_{\rm esc} = \sqrt{2} v_{\rm circ}$ for a point mass source of the gravitational potential.

Before we start modelling

Basics

Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit Energy per unit mass Kepler's Laws

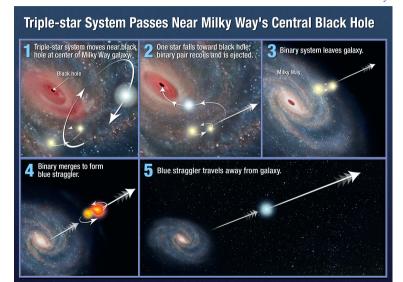
Escape velocity

Binary star orbi

General orbit under radia force law

Escape velocity

From the Galaxy



Before we start modelling

Basics

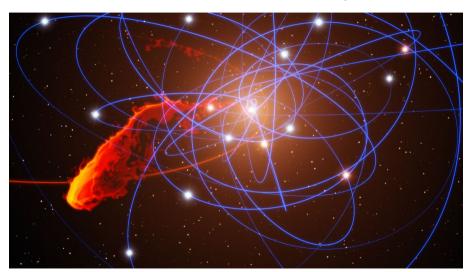
Newton's law Orbits Orbits in spherical potentials Equation of motion in two dimensions Path of the orbit Energy per unit mass Kepler's Laws Unbound orbits

Escape velocity

Binary star orb

General orbit under radia force law

Kepler orbits



Binary star orbits

General orbit under radia

Binary star orbits

- What we have done so far is assume a potential due to a fixed point mass which we take as being at the origin of our polar coordinates. We now wish to consider a situation in which we have two point masses, M_1 and M_2 both moving under the gravitational attraction of the other.
- This is a cluster of N stars where N=2 and we can solve it exactly! Hooray!
- The potential is no longer fixed at origin

$$\Phi(\mathbf{r}) = -\frac{GM_1}{|\mathbf{r} - \mathbf{r}_1|} - \frac{GM_2}{|\mathbf{r} - \mathbf{r}_2|}$$

Binary star orbits

General orbit under radial

Binary star orbits

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Binary star orbits

General orbit under radia force law

Binary star orbits

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$$\Phi(\mathbf{r}) = -\frac{GM_1}{|\mathbf{r} - \mathbf{r_1}|} - \frac{GM_2}{|\mathbf{r} - \mathbf{r_2}|}$$

Binary star orbits

General orbit under radia force law

Binary star orbits

Or the force acting on star 1, due to star 2 is

$$\mathbf{F_1} = \frac{GM_1M_2}{|\mathbf{r_1} - \mathbf{r_2}|^2}$$

in the direction of $r_2 - r_1$

$$\Rightarrow \mathsf{F_1} = \frac{GM_1M_2}{|\mathsf{r_1} - \mathsf{r_2}|^3}(\mathsf{r_2} - \mathsf{r_1})$$

And by symmetry (or Newton's 3rd law)

$$\mathsf{F_2} = rac{GM_1M_2}{|\mathsf{r_1} - \mathsf{r_2}|^3} (\mathsf{r_1} - \mathsf{r_2})$$

Binary star orbits

General orbit under radia force law

Binary star orbits

Then we know

$$M_1\ddot{\mathbf{r}}_1 = -\frac{GM_1M_2}{d^2}\hat{\mathbf{d}} \tag{1.39}$$

and

$$M_2\ddot{\mathbf{r}}_2 = -\frac{GM_1M_2}{d^2} \left(-\hat{\mathbf{d}}\right) \tag{1.40}$$

where

$$\mathbf{d} = \mathbf{r}_1 - \mathbf{r}_2 \tag{1.41}$$

is the vector from M_2 to M_1 .

Using these two we can write for $\ddot{\mathbf{d}} = \ddot{\mathbf{r}}_1 - \ddot{\mathbf{r}}_2$

$$\ddot{\mathbf{d}} = -\frac{G(M_1 + M_2)}{d^2}\hat{\mathbf{d}} \tag{1.42}$$

Binary star orbits

General orbit under radial force law

Binary star orbits

$$\ddot{\mathbf{d}} = -\frac{G(M_1 + M_2)}{d^2}\hat{\mathbf{d}}$$

which is identical to the equation of motion of a particle subject to a fixed mass $M_1 + M_2$ at the origin.

So we know that the period

$$T = 2\pi \sqrt{\frac{a^3}{G(M_1 + M_2)}} \tag{1.43}$$

where the size (maximum separation) of the relative orbit is 2a

Binary star orbits

General orbit under radia force law

Binary star orbits

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Before we start modelling stellar systems

Basics

Binary star orbits

General orbit under rad force law

Binary star orbits

If we take the coordinates for the centre of mass

$$\mathbf{r}_{\rm CM} = \frac{M_1}{M_1 + M_2} \mathbf{r}_1 + \frac{M_2}{M_1 + M_2} \mathbf{r}_2 \tag{1.44}$$

From equations (1.39) and (1.40) we know that

$$M_1\ddot{\mathbf{r}}_1 + M_2\ddot{\mathbf{r}}_2 = 0 \tag{1.45}$$

and so

$$\frac{d}{dt}\left(M_1\dot{\mathbf{r}}_1 + M_2\dot{\mathbf{r}}_2\right) = 0\tag{1.46}$$

or

$$(M_1\dot{\mathbf{r}}_1 + M_2\dot{\mathbf{r}}_2) = \text{constant} \tag{1.47}$$

i.e. $\dot{\mathbf{r}}_{\mathrm{CM}}=$ constant.

We can choose an inertial frame in which the centre of mass has zero velocity, so might as well do so

Before we start modelling stellar systems

Basics

Binary star orbits

General orbit under rac force law

Binary star orbits

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Binary star orbits

General orbit under radia force law

Binary star orbits

Note that choosing $\mathbf{r}_{\mathrm{CM}}=0\Rightarrow \mathcal{M}_1\mathbf{r}_1=-\mathcal{M}_2\mathbf{r}_2$, and so $\mathbf{r}_1=\mathbf{d}+\mathbf{r}_2=\mathbf{d}-\frac{\mathcal{M}_1}{\mathcal{M}_2}\mathbf{r}_1$ This $\Rightarrow \mathbf{r}_1=\frac{\mathcal{M}_2}{\mathcal{M}_1+\mathcal{M}_2}\mathbf{d}$ and similarly $\mathbf{r}_2=-\frac{\mathcal{M}_1}{\mathcal{M}_1+\mathcal{M}_2}\mathbf{d}$.

$$\mathbf{J} = M_{1}\mathbf{r}_{1} \times \dot{\mathbf{r}}_{1} + M_{2}\mathbf{r}_{2} \times \dot{\mathbf{r}}_{2}
= \frac{M_{1}M_{2}^{2}}{(M_{1} + M_{2})^{2}}\mathbf{d} \times \dot{\mathbf{d}} + \frac{M_{2}M_{1}^{2}}{(M_{1} + M_{2})^{2}}\mathbf{d} \times \dot{\mathbf{d}}
= \frac{M_{1}M_{2}}{M_{1} + M_{2}}\mathbf{d} \times \dot{\mathbf{d}}$$

(1.48)

50

$$\mathbf{J} = \mu \mathbf{h} \tag{1.49}$$

where μ is the reduced mass, and h is the specific angular momentum.

Binary star orbits

General orbit under radia force law

Binary star orbits

Note that choosing $\mathbf{r}_{\mathrm{CM}}=0\Rightarrow M_1\mathbf{r}_1=-M_2\mathbf{r}_2$, and so $\mathbf{r}_1=\mathbf{d}+\mathbf{r}_2=\mathbf{d}-\frac{M_1}{M_2}\mathbf{r}_1$. This $\Rightarrow \mathbf{r}_1=\frac{M_2}{M_1+M_2}\mathbf{d}$ and similarly $\mathbf{r}_2=-\frac{M_1}{M_1+M_2}\mathbf{d}$. The angular momentum \mathbf{J} (or \mathbf{H} if you want) is

$$\mathbf{J} = M_{1}\mathbf{r}_{1} \times \dot{\mathbf{r}}_{1} + M_{2}\mathbf{r}_{2} \times \dot{\mathbf{r}}_{2}
= \frac{M_{1}M_{2}^{2}}{(M_{1} + M_{2})^{2}} \mathbf{d} \times \dot{\mathbf{d}} + \frac{M_{2}M_{1}^{2}}{(M_{1} + M_{2})^{2}} \mathbf{d} \times \dot{\mathbf{d}}
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Before we start modelling

Rasics

Binary star orbits

General orbit under radial force law

Binary star orbits

Momentum loss due to mass loss



Galaxies Part II

Before we start modelling stellar systems

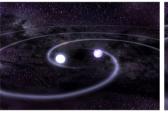
Basics

Binary star orbits

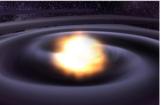
General orbit under radia

Binary star orbits

Momentum loss due to Gravitational Radiation







Before we start modelling

Basics

Binary star orbits

General orbit under radia force law

Binary star orbits Momentum loss due to Gravitational Radiation







Joseph H. Taylor Jr.

The Nobel Prize in Physics 1993 was awarded jointly to Russell A. Hulse and Joseph H. Taylor Jr. "for the discovery of a new type of pulsar, a discovery that has opened up new possibilities for the study of gravitation"

Photos: Copyright © The Nobel Foundation

Question: predict the evolution of the pulsar's orbit.

Galaxies Part II

Before we start modelling

Basics

Binary star orbits

General orbit under radia force law

Binary star orbits

Momentum loss due to Gravitational Radiation

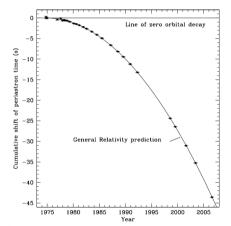


Figure 2. Orbital decay caused by the loss of energy by gravitational radiation. The parabola depicts the expected shift of periastron time relative to an unchanging orbit, according to general relativity. Data points represent our measurements, with error bars mostly too small to see.

Before we start modelling

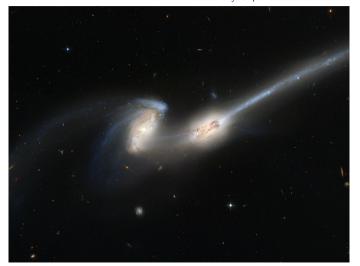
Basics

Binary star orbits

General orbit under radial force law

Binary star orbits

Binary Super-massive Black holes



Binary star orbits

General orbit under radial force law

Example

General orbit under radial force law

Remember the orbit equation?

$$\frac{d^2u}{d\phi^2} + u = -\frac{f(\frac{1}{u})}{h^2u^2} \tag{1.50}$$

where $u \equiv \frac{1}{r}$ and $f_r = f$ for a spherical potential. For f from a gravitational potential, we have

$$f\left(\frac{1}{u}\right) = -\frac{d\Phi}{dr} = u^2 \frac{d\Phi}{du} \tag{1.51}$$

since gravity is conservative.

There are two types of orbit:

- Unbound: $r \to \infty$, $u \ge 0$ as $\phi \to \phi_\infty$
- Bound: r (and u) oscillate between finite limits.

General orbit under radial

General orbit under radial force law

Energy

If we take (1.50) $\times \frac{du}{d\phi}$:

$$\frac{du}{d\phi}\frac{d^2u}{d\phi^2} + u\frac{du}{d\phi} + \frac{u^2}{h^2u^2}\frac{d\Phi}{du}\frac{du}{d\phi} = 0$$
 (1.52)

$$\Rightarrow \frac{d}{d\phi} \left[\frac{1}{2} \left(\frac{du}{d\phi} \right)^2 + \frac{1}{2} u^2 + \frac{\Phi}{h^2} \right] = 0 \tag{1.53}$$

and integrating over ϕ we have

$$\Rightarrow \frac{1}{2} \left(\frac{du}{d\phi} \right)^2 + \frac{1}{2} u^2 + \frac{\Phi}{h^2} = \text{constant} = \frac{E}{h^2}$$
 (1.54)

General orbit under radial force law

Energy

and using $h = r^2 \dot{\phi}$

$$\left(\frac{E}{h^2} = \frac{1}{2} \left(\frac{du}{d\phi}\right)^2 + \frac{1}{2}u^2 + \frac{\Phi}{h^2}\right)$$

$$E = \frac{r^4 \dot{\phi}^2}{2} \left(\frac{du}{d\phi}\right)^2 + \frac{1}{2}r^2 \dot{\phi}^2 + \Phi(r)$$

$$= \frac{r^4}{2} \left(\frac{du}{dt}\right)^2 + \frac{1}{2}r^2 \dot{\phi}^2 + \Phi(r)$$

$$= \frac{r^4}{2} \left(\frac{du}{dr}\dot{r}\right)^2 + \frac{1}{2}r^2 \dot{\phi}^2 + \Phi(r)$$

$$= \frac{1}{2}\dot{r}^2 + \frac{1}{2}r^2 \dot{\phi}^2 + \Phi(r)$$
(1.55)

i.e. we can show that the constant E we introduced is the energy per unit mass.

Binary star orbits

General orbit under radial force law

Example

General orbit under radial force law

Peri and Apo

$$\left(\frac{E}{h^2} = \frac{1}{2} \left(\frac{du}{d\phi}\right)^2 + \frac{1}{2}u^2 + \frac{\Phi}{h^2}\right)$$

For bound orbits, the limiting values of u (or r) occur where $\frac{du}{d\phi}=0$, i.e. where

$$u^2 = \frac{2E - 2\Phi(u)}{h^2} \tag{1.56}$$

from (1.54).

This has two roots, $u_1 = \frac{1}{r_1}$ and $u_2 = \frac{1}{r_2}$

this is not obvious, since Φ is not defined, but it can be proved - it is an Example!

For $r_1 < r_2$, where r_1 is the pericentre, r_2 the apocentre

Before we start modelling stellar systems

Basics

Dillary Star Orbits

Orbital periods

Example

Orbital periods

Radial motion

The radial period T_r is defined as the time to go from $r_2 \rightarrow r_1 \rightarrow r_2$. Now take (1.55) and re-write:

$$E = \frac{1}{2}\dot{r}^2 + \frac{1}{2}r^2\dot{\phi}^2 + \Phi(r)$$

$$\left(\frac{dr}{dt}\right)^2 = 2(E - \Phi(r)) - \frac{h^2}{r^2}$$
 (1.57)

where we used $h=r^2\dot{\phi}$ to eliminate $\dot{\phi}$

So

$$\frac{dr}{dt} = \pm \sqrt{2(E - \Phi(r)) - \frac{h^2}{r^2}} \tag{1.58}$$

(two signs - \dot{r} can be either > 0 or < 0, and $\dot{r} = 0$ at $r_1 \& r_2$.

Then

$$T_r = \oint dt = 2 \int_{r_1}^{r_2} \frac{dt}{dr} dr = 2 \int_{r_1}^{r_2} \frac{dr}{\sqrt{2(E - \Phi(r)) - \frac{h^2}{r^2}}}$$
 (1.59)

Before we start modelling stellar systems

Basics

Dillary star Orbits

force law Orbital periods

Example

Orbital periods

Radial motion

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(1.59)

Binary star orbits

General orbit under radial force law

Orbital periods

Example

Orbital periods

Azimuthal motion

If travelling from $r_2 \rightarrow r_1 \rightarrow r_2 \phi$ is increased by an amount

$$\Delta \phi = \oint d\phi = 2 \int_{r_1}^{r_2} \frac{d\phi}{dr} dr = 2 \int_{r_1}^{r_2} \frac{d\phi}{dt} \frac{dt}{dr} dr$$
 (1.60)

SO

$$\Delta \phi = 2h \int_{r_1}^{r_2} \frac{dr}{r^2 \sqrt{2(E - \Phi(r)) - \frac{h^2}{r^2}}}$$
 (1.61)

Binary star orbits

General orbit under radial

Orbital periods Example

Precession of the orbit

For a given orbit, the time taken to go around once (i.e. $0 \to 2\pi$) depends in general on where you start, so the azimuthal period is not well defined. Instead use the mean angular velocity $\bar{\omega} = \Delta \phi/T_r$ to obtain a mean azimuthal period T_ϕ , so

$$T_{\phi}=2\pi/ar{\omega}\Rightarrow T_{\phi}=rac{2\pi}{\Delta\phi}T_{r}$$

is the mean time to go around once.

Note that unless $\Delta \phi/2\pi$ is a rational number the orbit is not closed.

Binary star orbits

General orbit under radia

Orbital periods Example

Precession of the orbit

For Keplerian orbit $\Delta \phi = 2\pi \Rightarrow T_r = T_{\phi}$.

In one period T_r the apocentre (or pericentre) advances by an angle $\Delta \phi - 2\pi$. i.e.the orbit shifts in azimuth at an average rate given by the mean precession rate

$$\Omega_{\rho} = \frac{\Delta \phi - 2\pi}{T_r} \text{ rad s}^{-1}$$
 (1.62)

Thus the precession period is

$$T_{p} = \frac{2\pi}{\Omega_{p}} = \frac{T_{r}}{\frac{\Delta\phi}{2\pi} - 1} \tag{1.63}$$

This precession is in the sense opposite to the rotation of the star

In the special case of a Keplerian orbit $\Delta\phi=2\pi\Rightarrow T_\phi=T_r$ and $\Omega_p=0$, i.e. orbits are closed and do not precess. Otherwise general orbit is a rosette between $r_1\ \&\ r_2$. This allows us to visualize how we can build a galaxy out of stars on different orbits.

Before we start modelling

Basics

Binary star orbits

General orbit under radia

Orbital periods

Example

Precession of the orbit

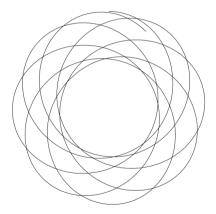


Figure 3.1 A typical orbit in a spherical potential (the isochrone, eq. 2.47) forms a rosette.

Example

 T_r for the Keplerian case $\Phi(r) = -\frac{GM}{r}$ We have equation (1.59)

$$T_r = 2 \int_{r_1}^{r_2} \frac{dr}{\sqrt{2(E - \Phi(r)) - \frac{h^2}{r^2}}}$$

$$2(E - \Phi(r)) - \frac{h^2}{r^2} = 0$$

$$2E + \frac{2GM}{r} - \frac{h^2}{r^2} = 0$$

$$r^2 + \frac{GM}{E}r - \frac{h^2}{2E} = 0$$

$$\Leftrightarrow (r-r_1)(r-r_2)=0$$

$$\Rightarrow r_1 r_2 = -\frac{h^2}{2F}; \quad r_1 + r_2 = -\frac{GM}{F}$$

Example

Before we start modellin stellar systems

Basics

Binary star orbits

Orbital perior

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$$T_r = 2 \int_{r_1}^{r_2} \frac{dr}{\sqrt{2(E - \Phi(r)) - \frac{h^2}{r^2}}}$$

Now $r_1 \& r_2$ are determined from $\dot{r} = 0$, i.e.

$$2(E - \Phi(r)) - \frac{h^2}{r^2} = 0$$

$$2E + \frac{2GM}{r} - \frac{h^2}{r^2} = 0$$

$$r^2 + \frac{GM}{E}r - \frac{h^2}{2E} = 0$$

$$\Leftrightarrow (r-r_1)(r-r_2)=0$$

$$\Rightarrow r_1 r_2 = -\frac{h^2}{2F}; \quad r_1 + r_2 = -\frac{GM}{F}$$

(remember E < 0 for a bound orbit).

(1.64)

(1.65)

(1.66)

(1.67)

(1.68)

Before we start modelling stellar systems

Basics

Binary star orbits

force law

Orbital perio

Rewrite (1.59) as

$$T_r = 2 \int_{r_1}^{r_2} \frac{r dr}{\sqrt{2E(r - r_1)(r - r_2)}} = \frac{2}{\sqrt{2|E|}} \int_{r_1}^{r_2} \frac{r dr}{\sqrt{(r_2 - r)(r - r_1)}}$$
(1.69)

if $r_1 < r < r_2$.

This is another of those integrals. If $R = a + bx + cx^2 = -r^2 + (r_1 + r_2)r - r_1r_2$ and $\Delta = 4ac - b^2$ which becomes, using the variables here, $\Delta = -(r_1 - r_2)^2$ then

$$\int \frac{xdx}{\sqrt{R}} = \frac{\sqrt{R}}{c} - \frac{b}{2c} \frac{1}{\sqrt{-c}} \sin^{-1} \left(\frac{2cx + b}{\sqrt{-\Delta}} \right)$$

for c < 0 and $\Delta < 0$ (See G&R 2.261 and 2.264).

Before we start modelling stellar systems

Basics

Binary star orbits

General orbit under radial

Orbital period

Example

The first term is 0 at r_1 and r_2 (R = 0 there), so

$$T_{r} = \frac{2}{\sqrt{2|E|}} \left[\frac{r_{1} + r_{2}}{2} \right] \left[\sin^{-1} \left(\frac{-2r_{2} + r_{1} + r_{2}}{r_{1} - r_{2}} \right) - \sin^{-1} \left(\frac{-2r_{1} + r_{1} + r_{2}}{r_{1} - r_{2}} \right) \right]$$

$$= \frac{2}{\sqrt{2|E|}} \left[\frac{r_{1} + r_{2}}{2} \right] \left[\sin^{-1}(1) - \sin^{-1}(-1) \right]$$

$$= \frac{2}{\sqrt{2|E|}} \frac{GM}{2(-E)} \left[\frac{\pi}{2} - \left(-\frac{\pi}{2} \right) \right]$$

$$= \frac{2\pi GM}{(-2E)^{\frac{3}{2}}}$$
(1.

(1.70)